

Explore the next sense



**Getting Started Guide
Acconeer XC111-XR111 &
XC112-XR112
Radar Sensor Evaluation Kit**

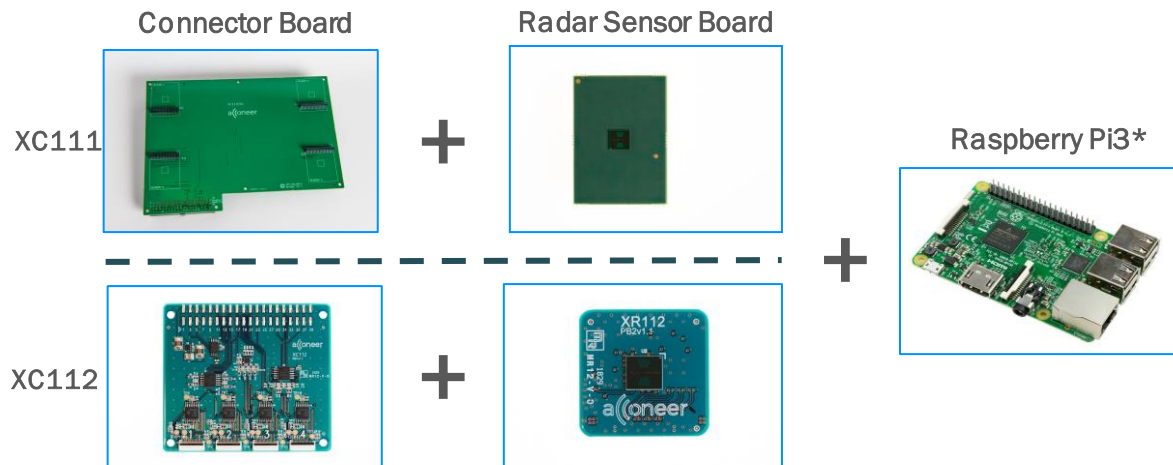
July 2018

Installation guide

This is an installation quick guide for the Acconeer XC111-XR111 and XC112-XR112 Radar Sensor Evaluation Kit (The EVK). For a hands-on instruction video, please visit https://youtu.be/OuKrm_RAV_c.

Preparing the HW Installation

To complete a successful installation of Aconeer EVK, the following HW components will be required:



Additionally*:

- SD Card
- SD Card Holder
- USB Keyboard
- USB Mouse
- Flex Cable, 1 per XR112
- Power Supply for Raspberry Pi**
- Monitor with HDMI cable

* Not provided by Aconeer except flex cable
 ** Raspberry Pi original Power Supply is recommended

Preparing the SW installation

The following applications will be required to complete an installation. Also, they will be very useful when working with the EVK Radar Sensor EVK. Please download and install.

- Acconeer SW for EVK: Available from <https://www.acconeer.com/products>

For all users (Windows, Linux, IOS)

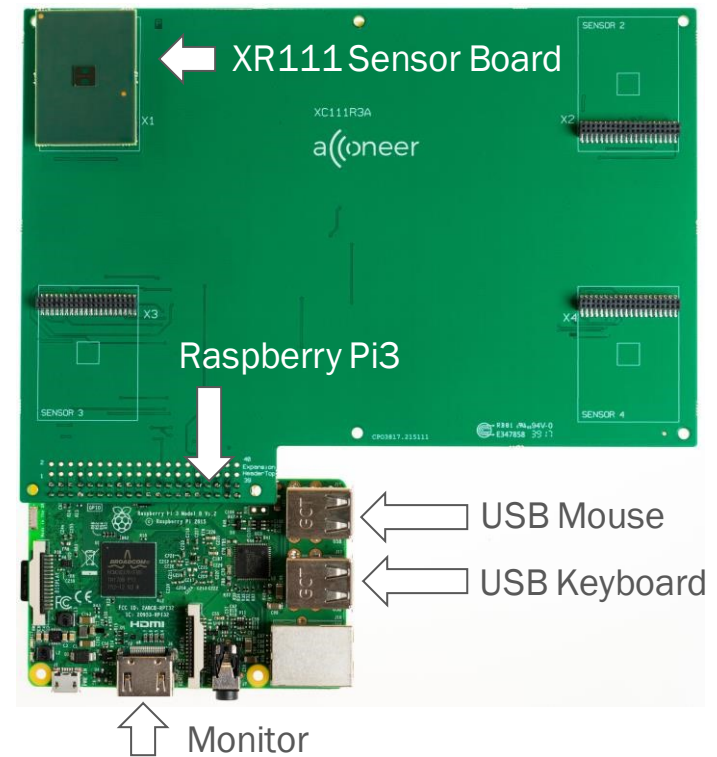
- Raspbian OS: Available from www.raspberrypi.org
- Etcher: Available from www.etcher.io for flashing the Raspbian OS

For Windows users (Linux/IOS users use SSH and SCP)

- PuTTY: Available from www.putty.org used for connecting to the Raspberry Pi
- WinSCP: Available from www.winscp.net used for transferring files to Raspberry Pi

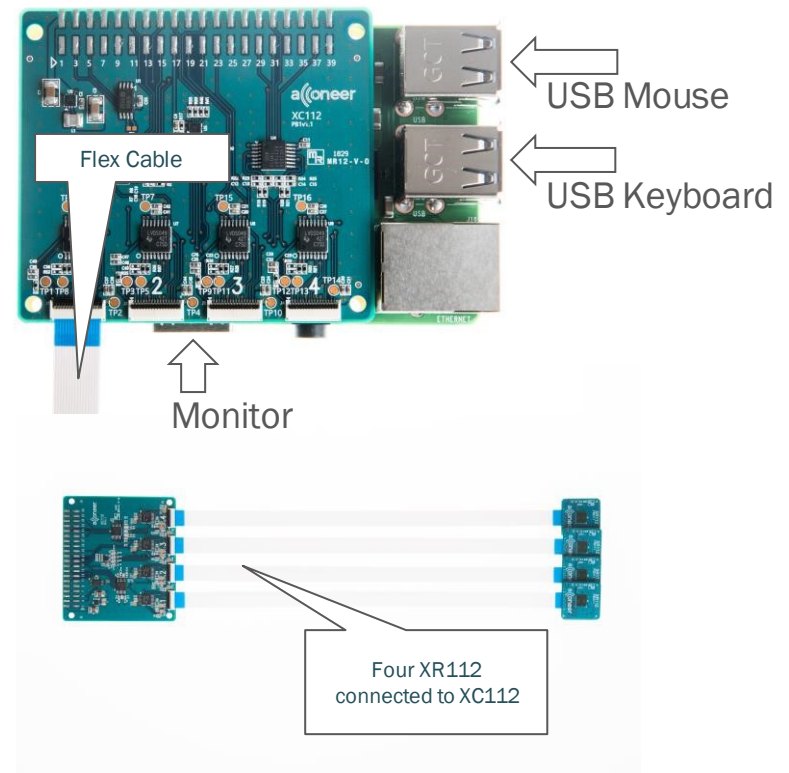
Assemble the HW XC111/XR111

- Connect the XR111 Radar Sensor Board to the XC111 Connector Board
- Connect the Raspberry Pi3 to the XC111 Connector Board
- The end result is illustrated here
- Also, connect mouse and keyboard as illustrated



Assemble the HW XC112/XR112

- Connect the XR112 Radar Sensor Board to the XC112 Connector Board using the provided flex cable.
- Connect the Raspberry Pi3 to the XC112 Connector Board
- Also, connect mouse and keyboard in the same way as on previous page



Installing the Raspbian

1. Insert the SD-Card in the PC. When prompted to format the card, please ignore/cancel.
2. Open Etcher
3. Drag the Raspbian flash image, zipped, to Etcher.
4. Make sure the SD card is the selected destination
5. Click flash. Flashing will begin and take a few minutes. When flashing is done, Etcher can be closed.



Depending on the security settings in Windows, you may need to click Yes in the confirmation popup to grant permission for the flashing process.

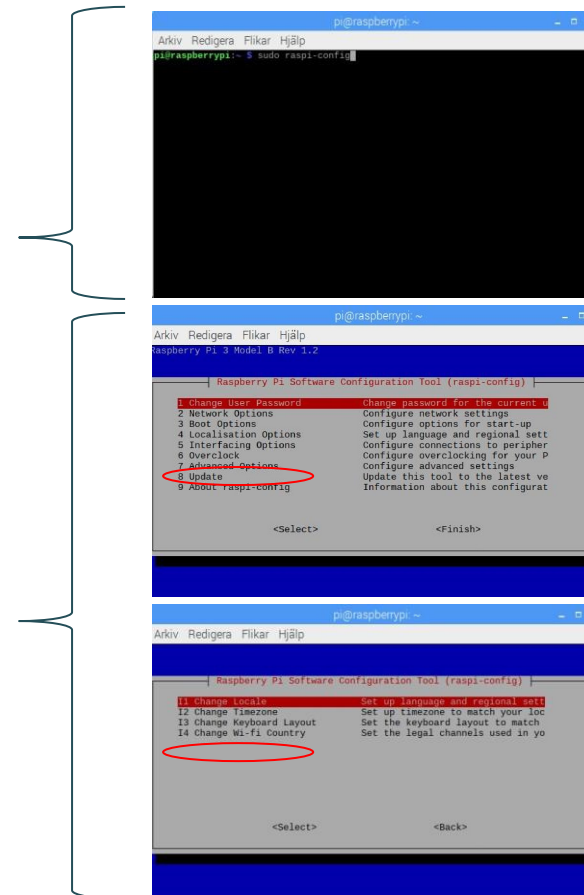
Installing Raspbian, cont.

1. Pull the SD card from the PC
2. Insert into the Raspberry Pi
3. Plug in the monitor, using the HDMI cable
4. Plug in the power supply to the Raspberry Pi
5. Boot of the Raspberry Pi will initiate automatically.

Installing the EVK

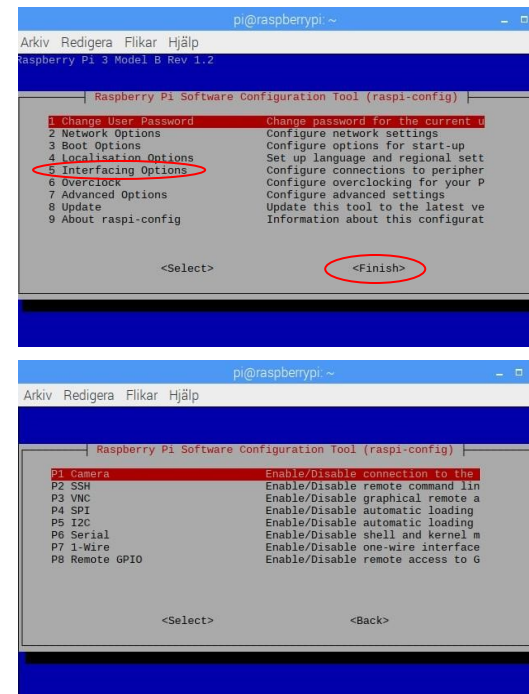
- Once booting is complete, you can start up the Raspberry Pi Terminal Window.
- On the prompt, type `sudo raspi-config`. The configuration menu will appear

-
- From the menu, choose #4 Localization options
 - And from the next menu; #2 Change Time zone
 - Set the appropriate Time zone



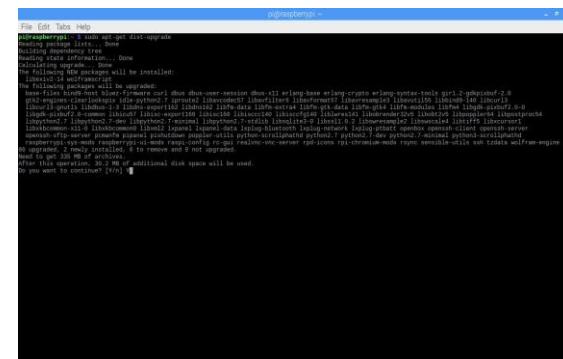
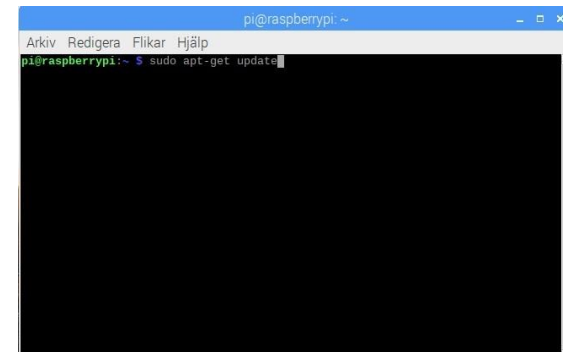
Installing Raspbian, cont.

- Go to #5 Interfacing options
- Enable the following interfaces:
 - P2 SSH
 - P4 SPI
 - P5 I2C
- When done, click <finish> (circled) to close the config menu



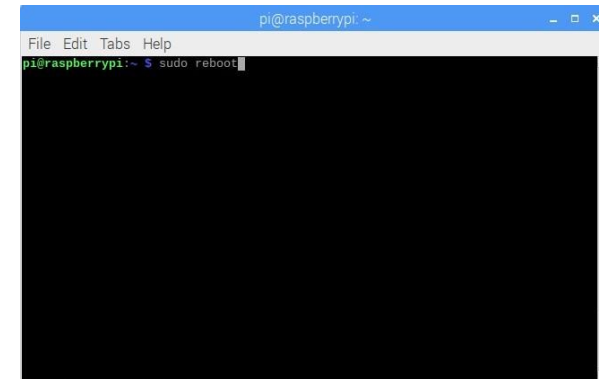
Installing Raspbian, cont.

- Make sure your PC and Raspberry Pi is connected to wifi. If that is not an option, use an Ethernet cable to connect your PC to the Raspberry Pi
- To make sure that you are using the latest version of Raspbian, type *sudo apt-get update*. This command will present the latest update
- Type *sudo apt-get dist-upgrade* to start the upgrade and confirm, when prompted, with a Y



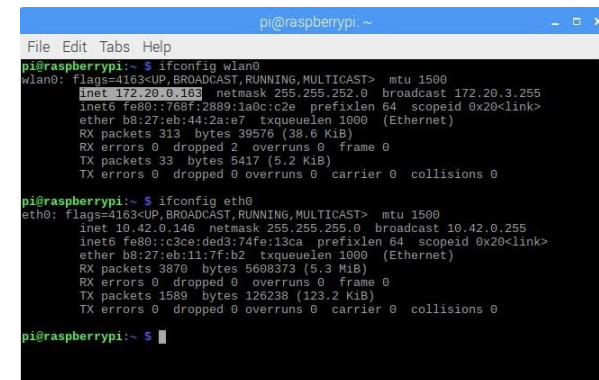
Installing Raspbian, cont.

- Once the command prompt appears, the installation is complete
- To reboot the Raspberry Pi, type *sudo reboot* in the console.
- Once the reboot has been done, open the terminal window again. Now we need to find the Raspberry Pi IP address.
 - Type *ifconfig wlan0* - the IP address will appear in the terminal window
 - If you do not use a wifi but have your raspberry connected by means of an Ethernet cable, type *ifconfig eth0*
 - In both cases, the Raspberry IP is visible as inet XXX.XX.X.XXX



```

pi@raspberrypi:~
File Edit Tabs Help
pi@raspberrypi:~ $ sudo reboot
  
```



```

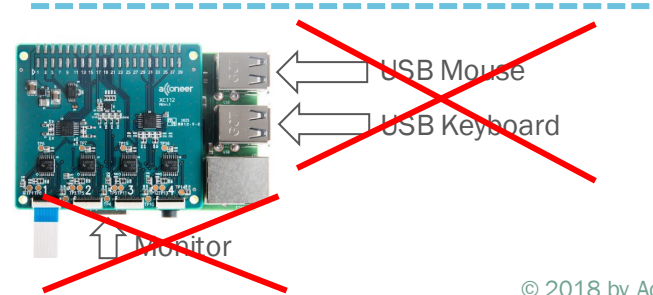
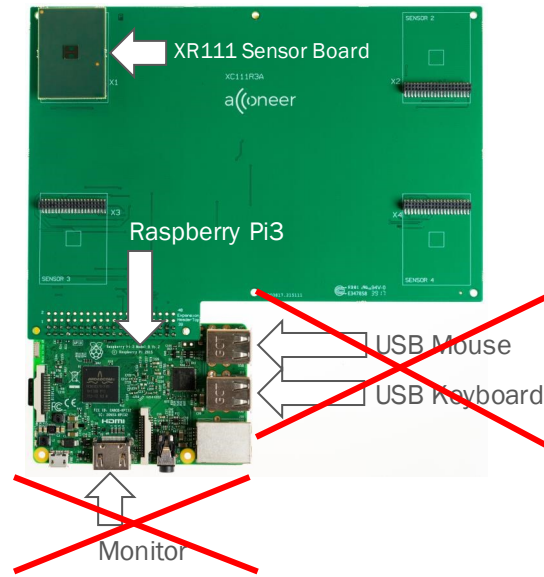
pi@raspberrypi:~ $ ifconfig wlan0
wlan0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 172.20.0.168 netmask 255.255.252.0 broadcast 172.20.3.255
    inet6 fe80::768f:2889:1a0c:c2e prefixlen 64 scopeid 0x20<link>
    ether b8:27:eb:44:2a:e7 txqueuelen 1000 (Ethernet)
    RX packets 313 bytes 39576 (38.6 KiB)
    RX errors 0 dropped 2 overruns 0 frame 0
    TX packets 33 bytes 5417 (5.2 KiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

pi@raspberrypi:~ $ ifconfig eth0
eth0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 10.42.0.146 netmask 255.255.255.0 broadcast 10.42.0.255
    inet6 fe80::e3ee:ded3:74fe:13ea prefixlen 64 scopeid 0x20<link>
    ether b8:27:eb:11:7f:b2 txqueuelen 1000 (Ethernet)
    RX packets 3870 bytes 5608373 (5.3 MiB)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 1589 bytes 126238 (123.2 KiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

pi@raspberrypi:~ $
  
```

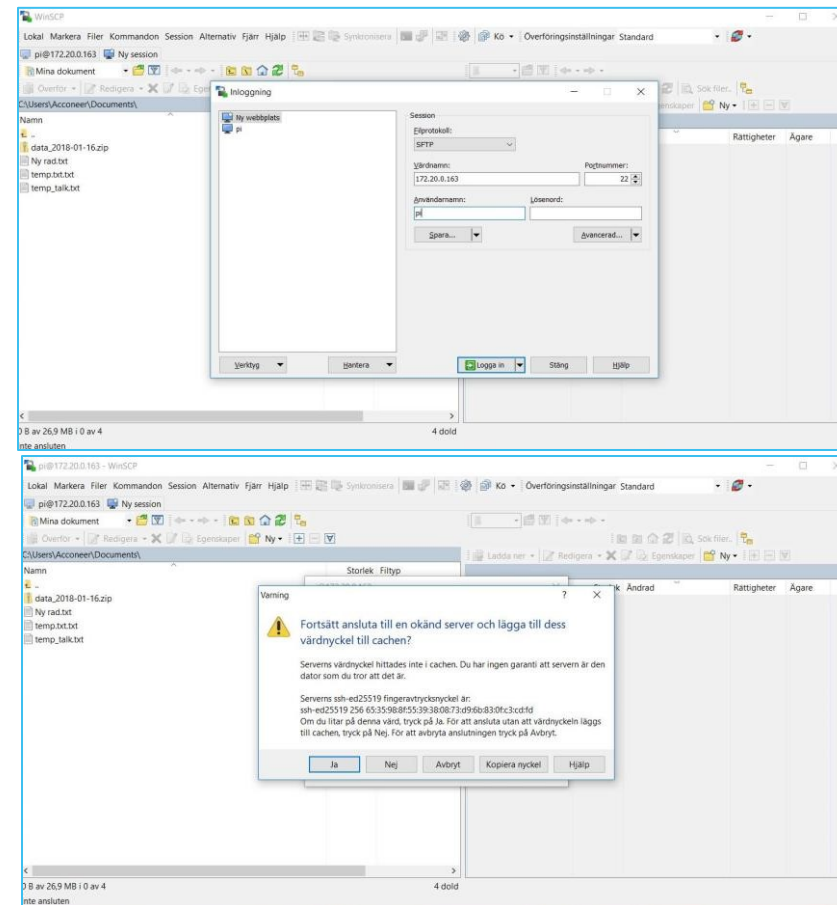
Installing Raspbian, cont.

- If everything is completed up to this point, you could disconnect both mouse and keyboard, as you now can control the setup remotely.
- Now let us continue by installing the Acconeer SW.



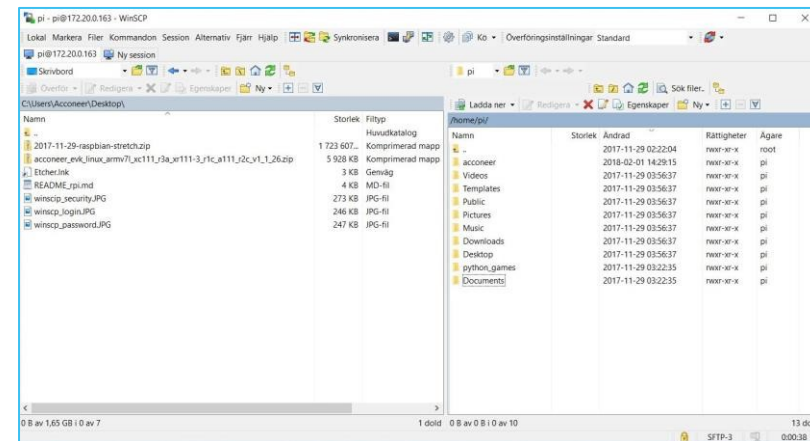
Installing the EVK SW

- Open up WinSCP
- For Host name, enter the IP address retrieved from the Raspberry Pi
- The Port should remain as default: 22
- Username and password are by default:
 - Username: pi
 - Password: raspberry
- Click Login
- If you receive a Warning, simply click Yes or Update.



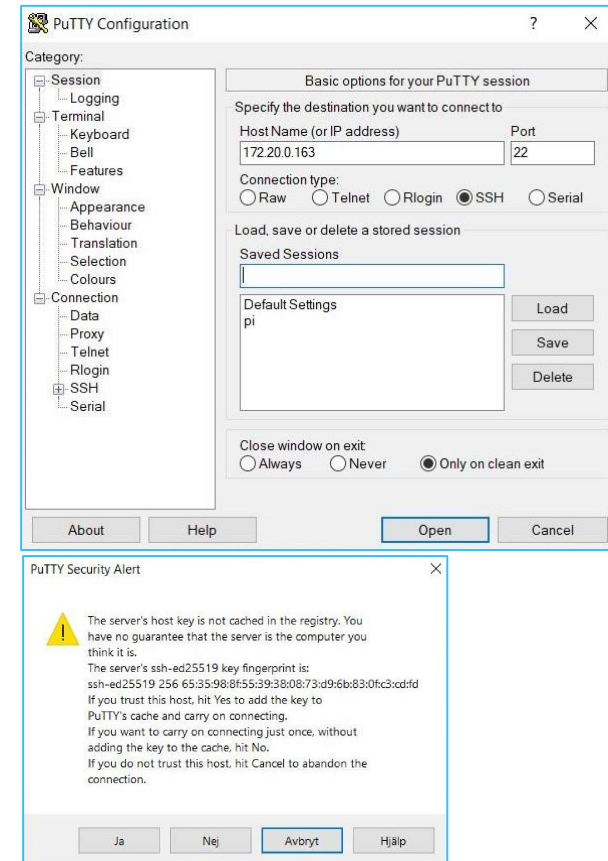
Installing the EVK Software

- Once logged in, you can see your local PC to the left and the Raspberry to the right.
- Locate the Acconeer SW zip on your local computer
- Drag the file to the raspberry and release it in the root.



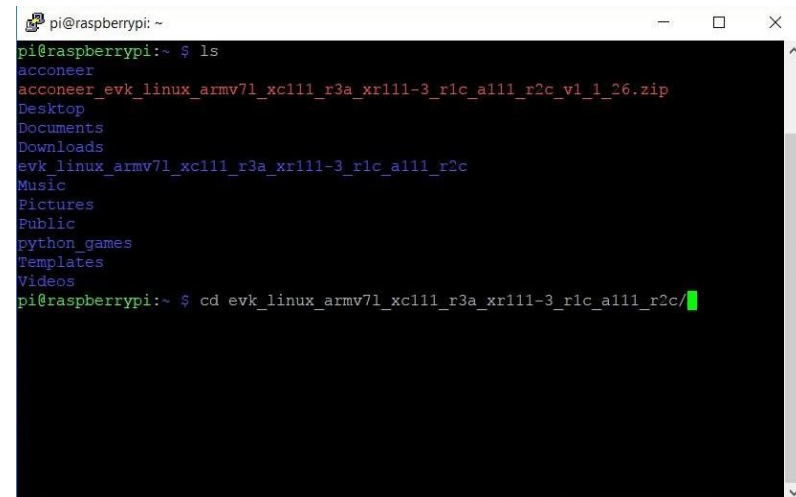
Installing the EVK Software

- Now open PuTTY.
- Enter the same IP address as previously and click Open.
- If prompted by a Warning, click Yes.



Installation the EVK Software

- A terminal window opens and you can login with the user name pi and password raspberry.
- The command `ls` will give you a list of all files/folders in the root of the raspberry.
- To unzip the Acconeer SW, type `sudo unzip [filename]`
- Once unzipped, you can enter the SW directory by using `sudo cd EVK....`



```

pi@raspberrypi: ~
pi@raspberrypi:~ $ ls
acconeer
acconeer_evk_linux_armv7l_xc111_r3a_xr111-3_r1c_a111_r2c_v1_1_06.zip
Desktop
Documents
Downloads
evk_linux_armv7l_xc111_r3a_xr111-3_r1c_a111_r2c
Music
Pictures
Public
python_games
Templates
Videos
pi@raspberrypi:~ $ cd evk_linux_armv7l_xc111_r3a_xr111-3_r1c_a111_r2c/

```

Installation the EVK Software

- From within the directory, you can activate different services.
- The illustration below shows activation of the distance detector:
`./out/example_detector_distance_rpi_xc111_r3a_xr111-3_r1c_a111_r2c*`

```

pi@raspberrypi: ~/evk_linux_armv7l_xc111_r3a_xr111-3_r1c_a111_r2c
pi@raspberrypi:~/evk_linux_armv7l_xc111_r3a_xr111-3_r1c_a111_r2c $ ./out/example_detector_distance_rpi_xc111_r3a_xr111-3_r1c_a111_r2c
18:37:28.062 [17716] (I) (example_detector_distance): Aconeer software version v1.1.26
18:37:28.434 [17717] (I) (message_router): Loaded internal driver (dummy)
18:37:28.437 [17716] (I) (aconeer): acc_start() Detected 4 sensor(s)
18:37:28.437 [17788] (I) (request_sensor_preparation): Performing sensor preparation, sensor 1
18:37:28.519 [17788] (I) (core_all1_r2c): Margin test status (99, 99, 100, 84)
18:37:28.566 [17788] (I) (acc_alg_dly_coarse_selection): Dly_coarse calibration status: 5 5 5
18:37:28.653 [17788] (I) (acc_alg_rx_fine_dip_selection): Rx_fine_dip calibration status: 45
18:37:28.842 [17788] (I) (acc_alg_area_selection): selected_area_index=2
18:37:28.937 [17788] (I) (core_all1_r2c): Offset calibration status: 10605
18:37:28.938 [17788] (I) (request_sensor_preparation): Sensor preparation done, sensor 1
18:37:28.941 [17716] (I) (example_detector_distance): Get distance from sensor 1, range 200-400 mm
18:37:28.941 [17789] (I) (core_all1_r2c): request_envelope: sensor 1 config: 7 1 12 0 0 3 1 1
18:37:28.972 [17789] (I) (request_envelope): Request running, sensor 1
18:37:28.973 [17789] (I) (request_envelope): Request stopped, sensor 1
18:37:28.981 [17716] (I) (example_detector_distance): Detector distance (200-400 mm): No object found
18:37:29.981 [17716] (I) (example_detector_distance): Get distance from sensor 1, range 200-400 mm
18:37:29.981 [17790] (I) (core_all1_r2c): request_envelope: sensor 1 config: 7 1 12 0 0 3 1 1
18:37:30.015 [17790] (I) (request_envelope): Request running, sensor 1
18:37:30.017 [17790] (I) (request_envelope): Request stopped, sensor 1
18:37:30.022 [17716] (I) (example_detector_distance): Detector distance (200-400 mm): No object found
^Cpi@raspberrypi:~/evk_linux_armv7l_xc111_r3a_xr111-3_r1c_a111_r2c $

```

*Please note that the path name might change slightly depending on SW version and HW variant.

Installation EVK SW

- The picture on the right-hand side shows how to start the envelope:
`./out/example_envelope_rpi_xc111_r3a_xr111-3_r1c_a111_r2c*`

*Please note that the path name might change slightly depending on SW version and HW variant.

```

pi@raspberrypi: ~/evk_linux_armv7/xc111_r3a_xr111-3_r1c_a111_r2c
pi@raspberrypi:~/evk_linux_armv7/xc111_r3a_xr111-3_r1c_a111_r2c $ ./out/example_envelope_rpi_xc111_r3a_xr111-3_r1c_a111_r2c
18:38:25.669 [17852] (I) (example_envelope): Aconeer software version v1.1.26
18:38:26.082 [17853] (I) (message_router): Loaded internal driver (dummy)
18:38:26.085 [17852] (I) (aconeer): acc_start() Detected 4 sensor(s)
18:38:26.086 [17924] (I) (request_sensor_preparation): Performing sensor preparation, sensor 1
18:38:26.167 [17924] (I) (core_all1_r2c): Margin test status (100, 100, 100, 81)
18:38:26.214 [17924] (I) (acc_alg_dly_coarse_selection): Dly coarse calibration status: 5 5 5
18:38:26.301 [17924] (I) (acc_alg_rx_fine_dip_selection): Rx fine dip calibration status: 45
18:38:26.490 [17924] (I) (acc_alg_area_selection): selected area index=1
18:38:26.585 [17924] (I) (core_all1_r2c): Offset calibration status: 10451
18:38:26.585 [17924] (I) (request_sensor_preparation): Sensor preparation done, sensor 1
18:38:26.589 [17852] (I) (example_envelope): Get envelope from sensor 1
18:38:26.589 [17925] (I) (core_all1_r2c): request_envelope: sensor 1 config: 7 1 12 0 0 3 1 1
18:38:26.620 [17925] (I) (request_envelope): Request running, sensor 1
18:38:26.621 [17925] (I) (request_envelope): Request stopped, sensor 1
18:38:26.629 [17852] (I) (example_envelope): Actual start range: 60 mm
18:38:26.629 [17852] (I) (example_envelope): Actual end range: 400 mm
  815      911      1009      1108      1206      1303      1397      1488
 1574      1655      1732      1802      1868      1928      1982      2032
 2076      2116      2151      2183      2211      2236      2258      2278
 2296      2312      2327      2340      2353      2365      2377      2387
 2397      2406      2415      2422      2427      2431      2432      2431
 2428      2421      2412      2400      2384      2366      2345      2321
 2294      2265      2234      2202      2167      2132      2096      2059
 2021      1983      1944      1906      1867      1828      1789      1750
 1710      1671      1632      1593      1554      1515      1476      1438
 1399      1361      1322      1284      1247      1209      1172      1136
 1100      1064      1029      994      960      927      894      861
  830      798      768      738      708      680      651      624
  597      570      544      518      493      469      445      421
  399      377      356      335      316      297      280      264
  249      236      224      214      205      197      191      187
  184      182      181      181      182      184      186      188
  190      193      195      196      198      198      198      198
  196      194      191      187      182      177      171      164
  157      149      141      133      125      117      110      103
  97      92      88      85      83      82      82      83
  85      89      93      98      104      111      118      126
  134      142      151      159      168      177      186      195
  204      213      221      229      237      245      252      258
  265      270      275      280      283      287      289      291
  292      293      293      292      291      289      286      282
  278      274      269      263      257      251      244      237
  230      222      215      208      201      194      187      181
  175      169      164      160      156      153      150      148
  146      145      144      144      145      145      146      147
  149      151      153      155      157      159      162      164
  166      169      171      173      175      176      178      178
  179      179      178      177      175      172      169      165
  161      156      151      145      140      135      129      125

```

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